

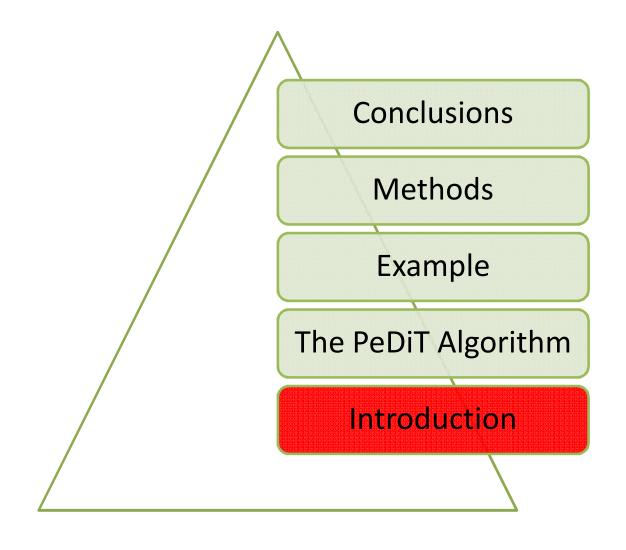
# Distributed Decision Tree Induction in

#### Peer-to-Peer Systems

Kanishka Bhaduri \* Ran Wolff \* Chris Giannella \*Hillol Kargupta

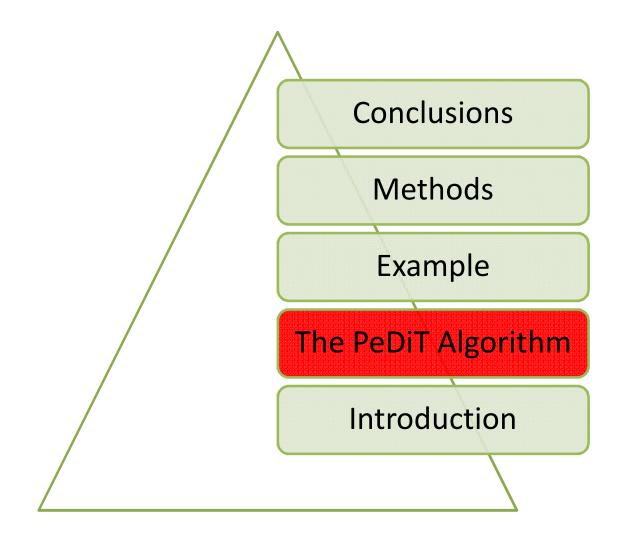
Aktuelle Arbeiten des Data Mining

Student: Simona Florescu 26.05.2009



# Introduction

- Motivation
- Goal
- Algorithm Overview



- Goal: to select the best attribute --> an adhoc decision tree with active nodes + developing of the peer-to-peer decision tree.
- Active node: the root and any node whose parent is split by the ad-hoc attribute value computed by the P2P misclassification minimization (P2PMM).
- Inactive: the rest of the nodes.

**Input:** S — a set of learning examples,  $\tau$  — mitigation delay **Initialization:** 

Create a root leaf and let  $root.S \leftarrow S$ . Set  $nodes \leftarrow \{root\}$ . Push root to queue Send BRANCH message to self with delay  $\tau$ 

- •As an input we take the training samples and a  $\tau$  the time interval for the further development.
- •We create an empty queue where we store all the new created nodes.

#### On BRANCH message:

```
Send BRANCH message to self with delay \tau
For (i \leftarrow 0, \ell \leftarrow null; i < queue.length \text{ and not active}(\ell); i++)
Pop head of queue into \ell
If not active(\ell)
enqueue \ell
If active(\ell)
Let A^j be the ad-hoc solution of P^2MM for \ell
call \mathbf{Branch}(\ell,j)
```

•We find the next active node and call the Branch procedure for that new node.

```
On data message \langle n, data \rangle:

If n \notin nodes

store \langle n, data \rangle in out - of - context

Else

Transfer the data to the P^2MM instance of n

If active(n) then

Process(n)
```

- •All the messages who come in the context of a not yet developed node are stored into a out-of-context Queue.
- •Later, when that node will be new created it will look up in the out-of-context Queue to check for its messages and process them.

# Procedure Active(n): If n = null or n = rootreturn true Let $A^j$ be the ad-hoc solution for $P^2MM$ for n.parentIf $n \not\in n.parent.sons[j]$ return false Return Active(n.parent)

•The procedure checks whether a node is active or not.

push n to the tail of the queue

```
Procedure Process(n):

Perform tests required by P^2MM for n and send any resulting messages

Let A^j be the ad-hoc solution for P^2MM for n

If n.sons[j] is not empty

for each m \in n.sons[j]

call Process(m)

Else
```

•All the precedent nodes who are not active are inserted at the tail of the Queue

#### **Procedure Branch** $(\ell, j)$ :

```
Create two new leaves \ell_0 and \ell_1

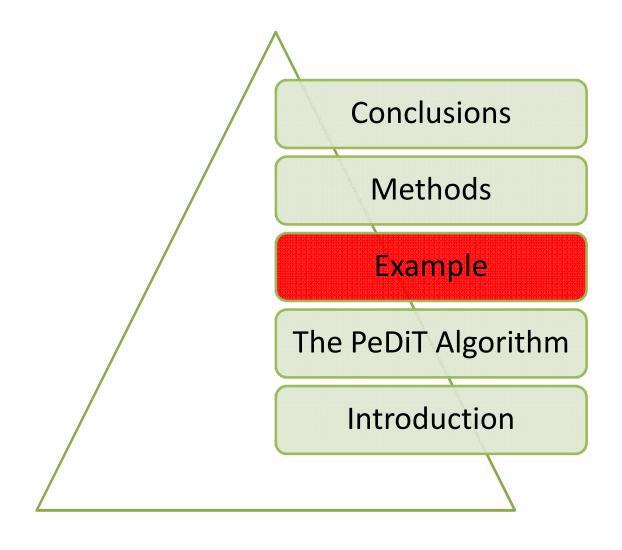
Set \ell_0.parent \leftarrow \ell, \ell_1.parent \leftarrow \ell

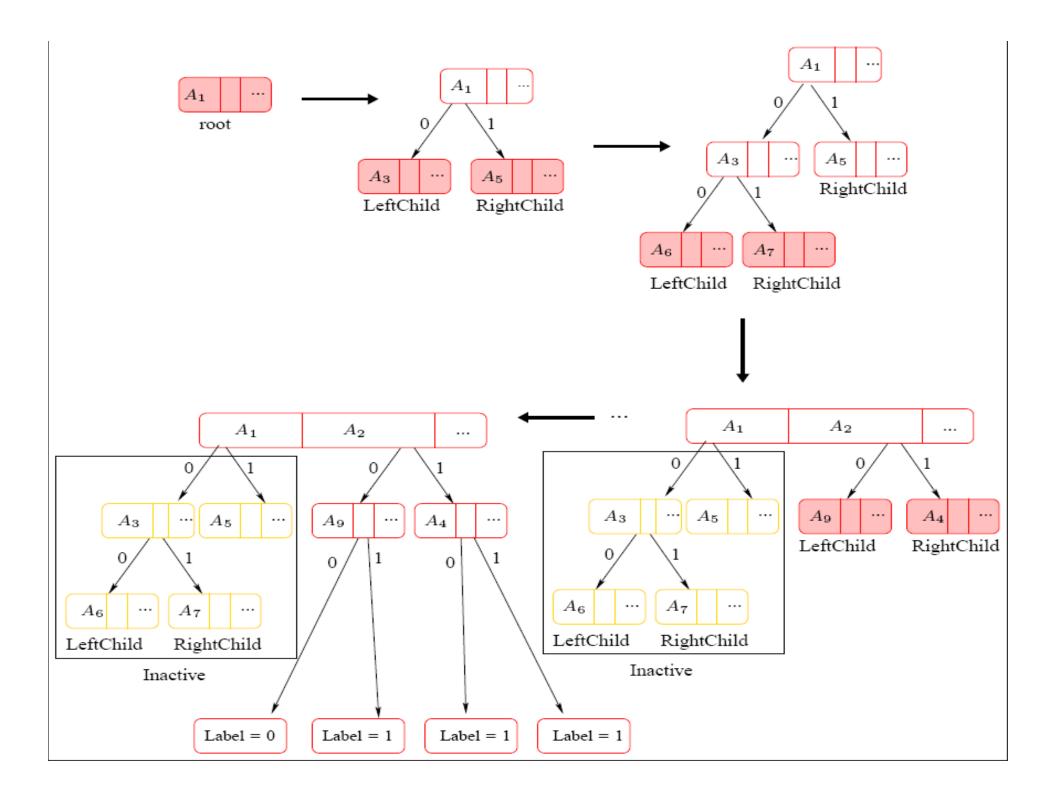
Set \ell_0.S \leftarrow \{s \in \ell.S : s[j] = 0\} and \ell_1.S \leftarrow \{s \in \ell.S : s[j] = 1\}
```

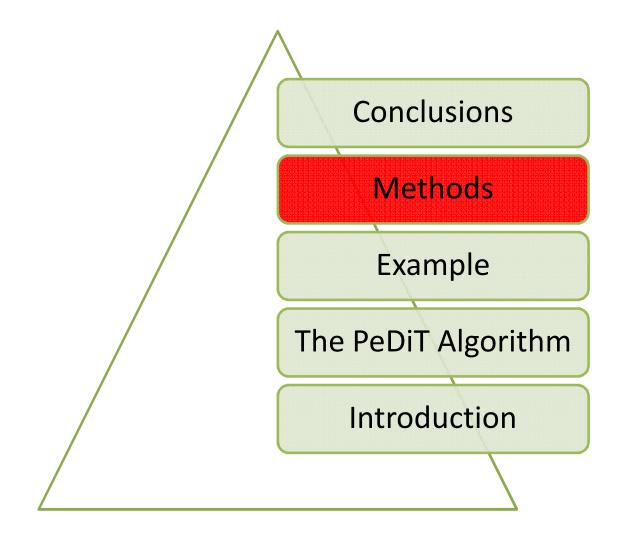
Remove from out - of - context messages intended for  $\ell_0$  and  $\ell_1$  and deliver the data to the respective instance of  $P^2MM$ 

Set  $\ell.sons[j] = {\ell_0, \ell_1}$ , add  $\ell_0, \ell_1$  to nodes and push  $\ell_0$  and  $\ell_1$  to the tail of the queue

- •It develops the tree with the new root and it checks for messages belonging to the respective node and it process them.
- •It pushes the precedent sons of the node into the tail of the queue.







- Returns the "AD-HOC" attribute with the highest misclassification gain
- Input: we consider as an input only the direct neighbors of a peer and the learning examples.
- Strategy: We compute the best attribute using the peer information and the misclassification gain and pivoting method.

•The algorithm takes as an input the peer k and its direct neighbors and the set of samples.

**Input variables of peer** k: the set of neighbors —  $N_k$ , the set of examples —  $S_k$  **Output variables of peer** k: the attribute  $A^{pivot}$  **Initialization**:

- For every  $A^i$  in  $A^1 
  ldots A^d$  initialize two instances of LSD-Majority with inputs  $x_{k,00}^i x_{k,01}^i$  and  $x_{k,10}^i x_{k,11}^i$ . Denote these instances by  $M_0^i$  and  $M_1^i$  respectively and let  $M_0^i 
  ldots \Delta_k$  and  $M_1^i 
  ldots \Delta_k$  denote the knowledge of those two instances. Further, for every  $\ell \in N_k$ , let  $M_0^i 
  ldots \Delta_{k,\ell}$  and  $M_1^i \Delta_{k,\ell}$  be their agreement.
- •For every attribute Ai we denote 2 instances of LSD(large-scale distributed) Majority: in order to determine  $S_0^i$  and  $S_1^i$
- •Their agreements are obtained by multiplying them with the exchanged information between 2 nodes,  $\Delta_{k,l}$

Initialization: Step 2

• For every  $a,b,c,d \in \{-1,1\}$  and every  $A^i,A^j \in [A^1\dots A^d]$  initialize an instance of LSD-Majority with input  $\delta_k^{i,j}|abcd$ . Denote these instances by  $M_{abcd}^{i,j}$ . Let  $M_{abcd}^{i,j}.\Delta_k$  and  $M_{abcd}^{i,j}\Delta_{k,\ell}$  ( $\forall \ell \in N_k$ ) be the knowledge and agreement of the  $M^{i,j}$  instance, respectively. Specifically denote  $M^{i,j}.\Delta_k$  and  $M^{i,j}\Delta_{k,\ell}$  the instance with a,b,c, and d equal to  $s_{k,0}^i,s_{k,1}^i,s_{k,0}^j$ , and  $s_{k,1}^j$ , respectively.

Secondly, we initialize the sixteen possible combinations from the values  $s_0^i$ ,  $s_1^i$ ,  $s_0^j$ ,  $s_1^j$  for every pair i<j  $\in$  {1,..d}

#### On any event:

- For  $A^i \in \{A^1 \dots A^d\}$  and every  $\ell \in N_k$ 
  - If not  $M_0^i \cdot \Delta_k \leq M_0^i \cdot \Delta_{k,\ell} < 0$  and not  $M_0^i \cdot \Delta_k \geq M_0^i \cdot \Delta_{k,\ell} \geq 0$  call  $Send(M_0^i,\ell)$
  - If not  $M_1^i \cdot \Delta_k \leq M_1^i \cdot \Delta_{k,\ell} < 0$  and not  $M_1^i \cdot \Delta_k \geq M_1^i \cdot \Delta_{k,\ell} \geq 0$  call  $Send(M_1^i,\ell)$

After the initialization the algorithm takes the following cases into consideration (events) (DMV):

- k experiences a data change or a change of its neighborhood
- k receives a message from a neighbor
- If the message condition (\*\*) is not satisfied then it calls the send message function.

Next, the pivoting method is used to reduce complexity.

- Do  $\text{ Let } pivot = \arg\max_{i \in [1...d]} \left\{ \max_{\ell \in N_k, j < i, m > i} \left\{ M^{j,i}.\Delta_{k,\ell}, -M^{i,m}.\Delta_{k,\ell} \right\} \right\}$   $\text{ For } A^i \in \left\{ A^1 \dots A^{pivot-1} \right\} \text{ and every } \ell \in N_k$   $* \text{ If not } M^{i,pivot}.\Delta_k \leq M^{i,pivot}.\Delta_{k,\ell} < 0 \text{ and not } M^{i,pivot}.\Delta_k \geq M^{i,pivot}.\Delta_{k,\ell} \geq 0 \text{ call } Send\left(M^{i,pivot},\ell\right)$   $\text{ For } A^i \in \left\{ A^{pivot+1} \dots A^d \right\} \text{ and every } \ell \in N_k$   $* \text{ If not } M^{pivot,i}.\Delta_k \leq M^{pivot,i}.\Delta_{k,\ell} < 0 \text{ and not } M^{pivot,i}.\Delta_k \geq M^{pivot,i}.\Delta_{k,\ell} \geq 0 \text{ call } Send\left(M^{pivot,i},\ell\right)$
- The chosen pivot is the attribute with the largest  $M^i$  value for j<i or the smallest  $M^{i,m}$  for i<m.
- If the pivoting condition fails, then it is called the Send function.

• While *pivot* changes

#### On message $(id, \delta)$ from $\ell$ :

- Let M be a majority voting instance with M.id = id
- Set  $M.\delta_{\ell,k}$  to  $\delta$

#### **Procedure Send** $(M, \ell)$ :

- $M.\delta_{k,\ell} = \alpha M.\Delta_k + M.\delta_{\ell,k}$
- Send to  $\ell$   $(M.id, M.\delta_{k,\ell})$

•In the Send procedure the  $\Delta k$ ,1 becomes  $\alpha \Delta k$  where  $\alpha$  is set by default to 1/2

# Distributed majority voting

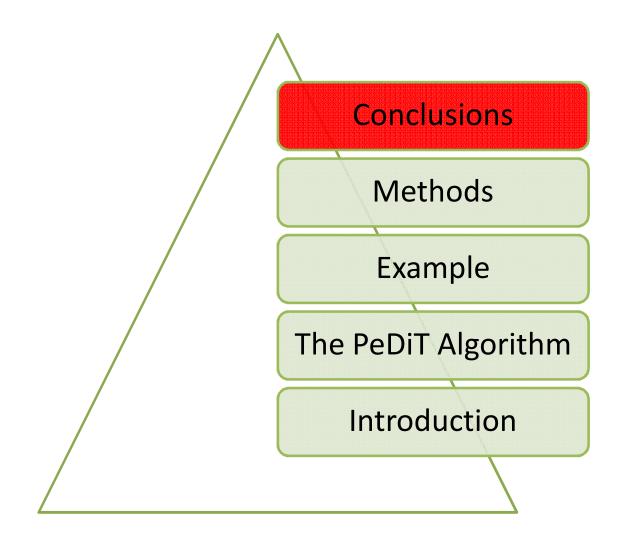
- Goal: to decide when a peer must send a message to a neighbor after detecting an event.
- Each peer k contains a real number :  $\delta^k$
- The latest message sent from a neighbor I to k :  $\delta^{lk}$
- $\Rightarrow \Delta^k = \delta^k + \sum_{l \in N_k} \delta^{lk}$
- All the exchanged information between k and a neighbor I :  $\Delta^{kl}$

# Distributed majority voting

The condition when k would send a message to l :

$$(\Delta^{kl} \ge 0 \land \Delta^{kl} > \Delta^k) \lor (\Delta^{kl} < 0 \land \Delta^{kl} < \Delta^k) \quad (*)$$

- When a message is sent :  $\Delta^{kl} = \alpha \Delta^k$  where  $\alpha$  is a parameter between 0 and 1 set by default to ½.
- Leaky bucket mechanism: it introduces time space between messages sending.



#### Conclusions

- The PeDiT Algorithm derivates from the standard decision tree induction algorithm except that it uses a misclassification gain as a splitting criteria and it uses a stopping rule the depth of the tree.
- Experiments show :
- a modest accuracy loss of the misclassification gain compared to Entropy criteria.
- the depth could decrease the efficiency of the algorithm but a depth of 3 it is an optimal choice.

#### Conclusions

- The PeDiT Algorithm is suitable for networks with millions of peers.
- Even if the number of attributes is increased, the algorithm remains moderate.
- With a sufficient given time the algorithm obtains from a P2P network the same result tree if given all the data of all the peers.

Thank you!

**THE END**